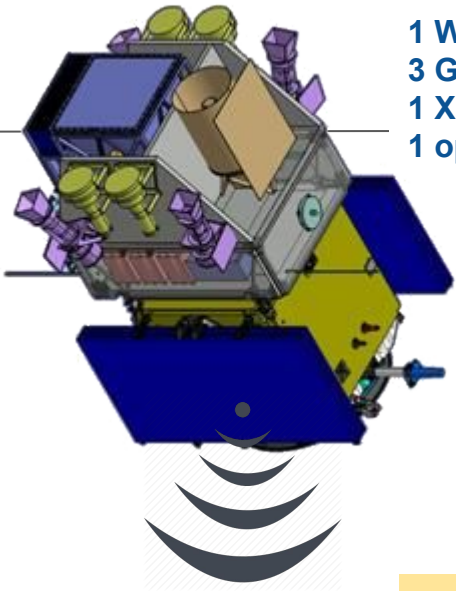


Annotating FITS Files with VO tags *SVOM case*

Laurent Michel - Mireille Louys
Strasbourg Observatory

- 1 Wide field Gamma Ray camera
- 3 Gamma Ray monitors
- 1 X-ray camera
- 1 optical telescope



X-Band data
Downlink 6 times a day

Fast alert data
Transmitted through a worldwide VHF network
Notifications carried out by VOEvents

Follow-up Data
2 ground IR and visible telescopes
China and Mexico
Transmitted through a dedicated link



SUOM

Ground segment

China and France (FSC)

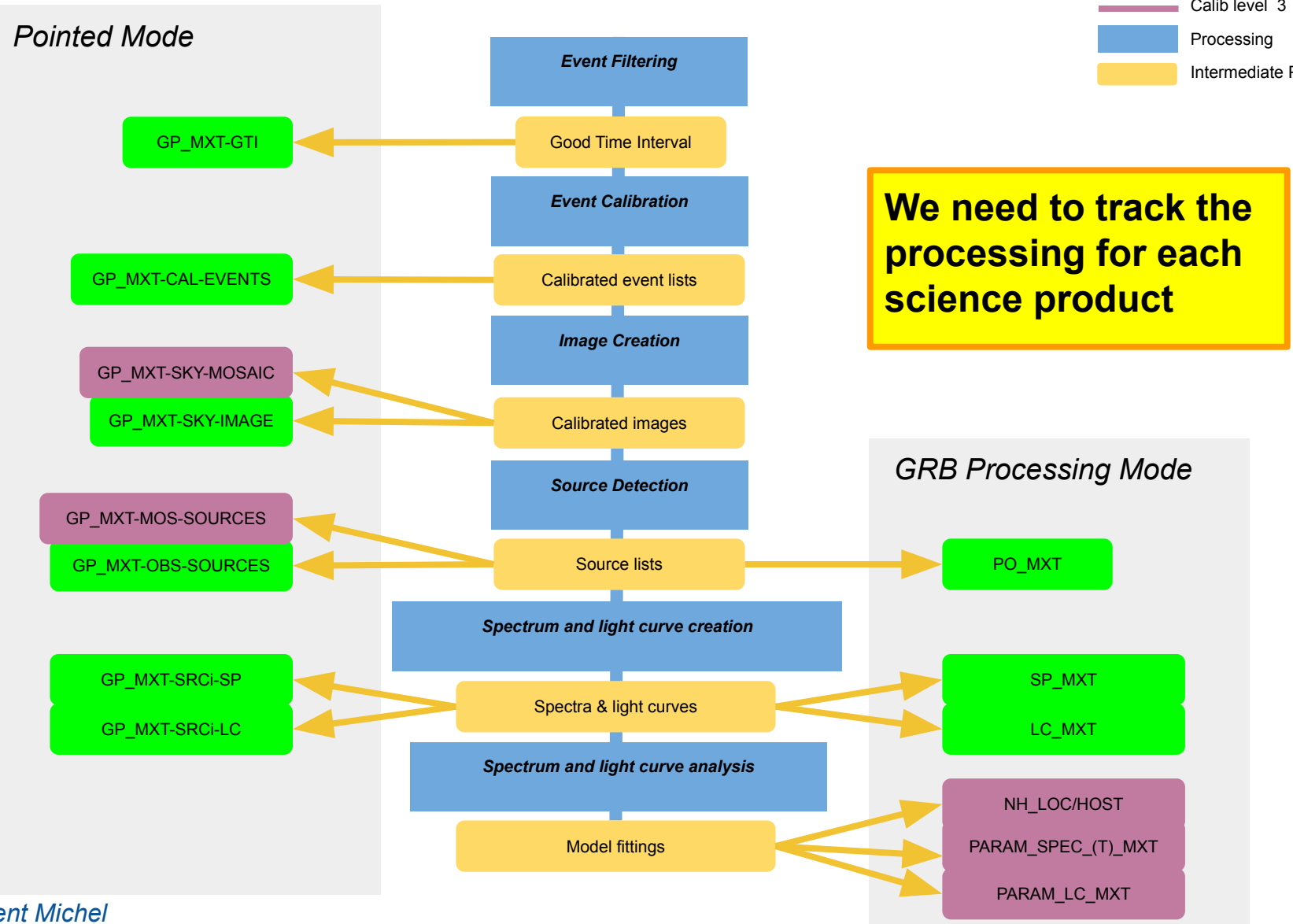
The SVOM mission

VO in FITS at a Glance

- **All SVOM science products are in FITS format**
 - Mission requirement
- **Why VO tags in FITS files?**
 - OBSCORE: Facilitate the publishing in VO collections
 - PROVENANCE: Facilitate the reprocessing with a different setup
- **Guideline**
 - Clear separation between native data (OGIP kws, Mission data, science data) and VO stuff
 - One FITS extension for the VO: VO-TAGS
 - Obscore as a set of keywords
 - Provenance: JSON serialization in a 1x1 ASCII table
- **Tools**
 - A python module to write and read data annotations
 - Not public yet

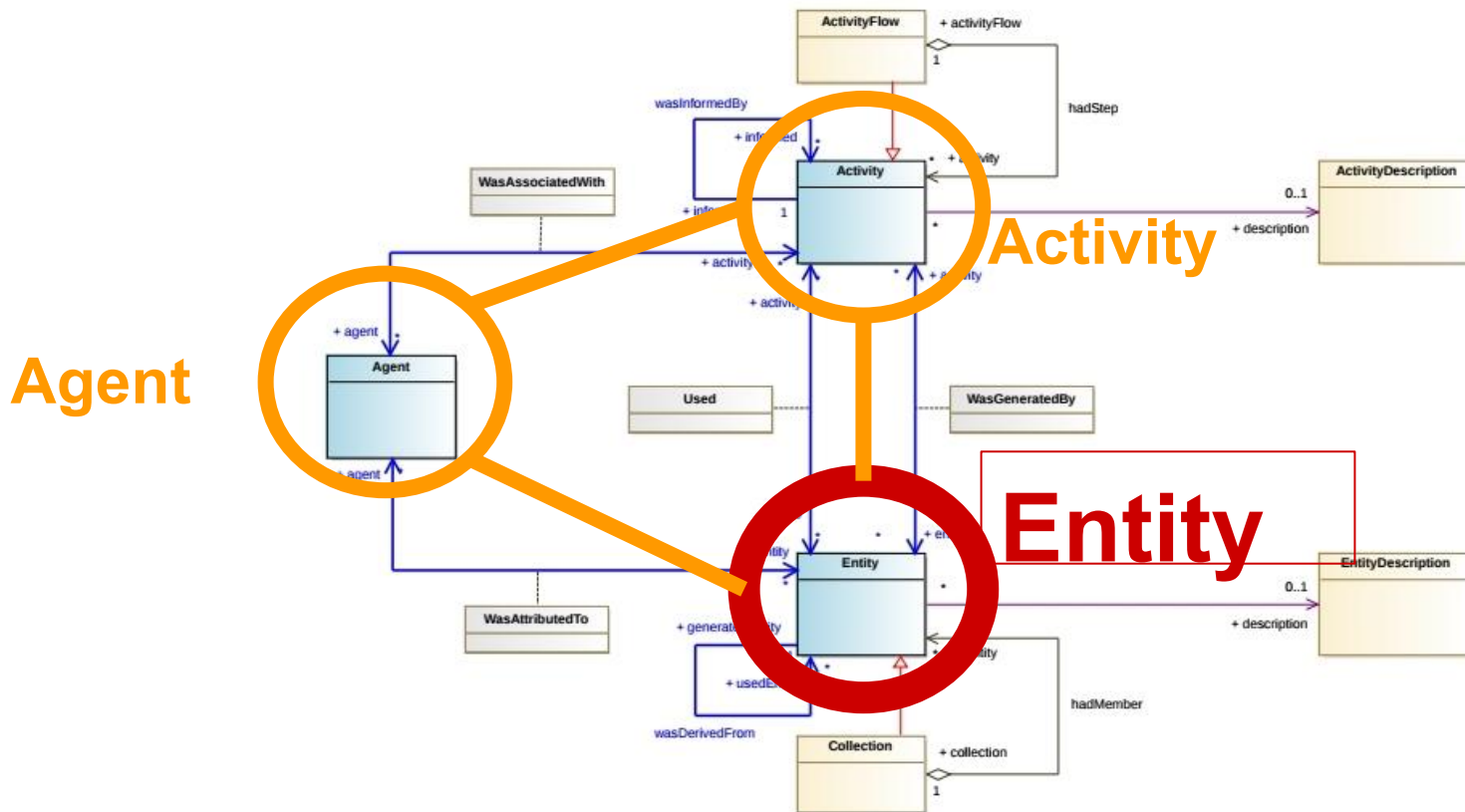
Provenance: Pipeline Workflow

- Calib Level 2
- Calib level 3
- Processing
- Intermediate Prds

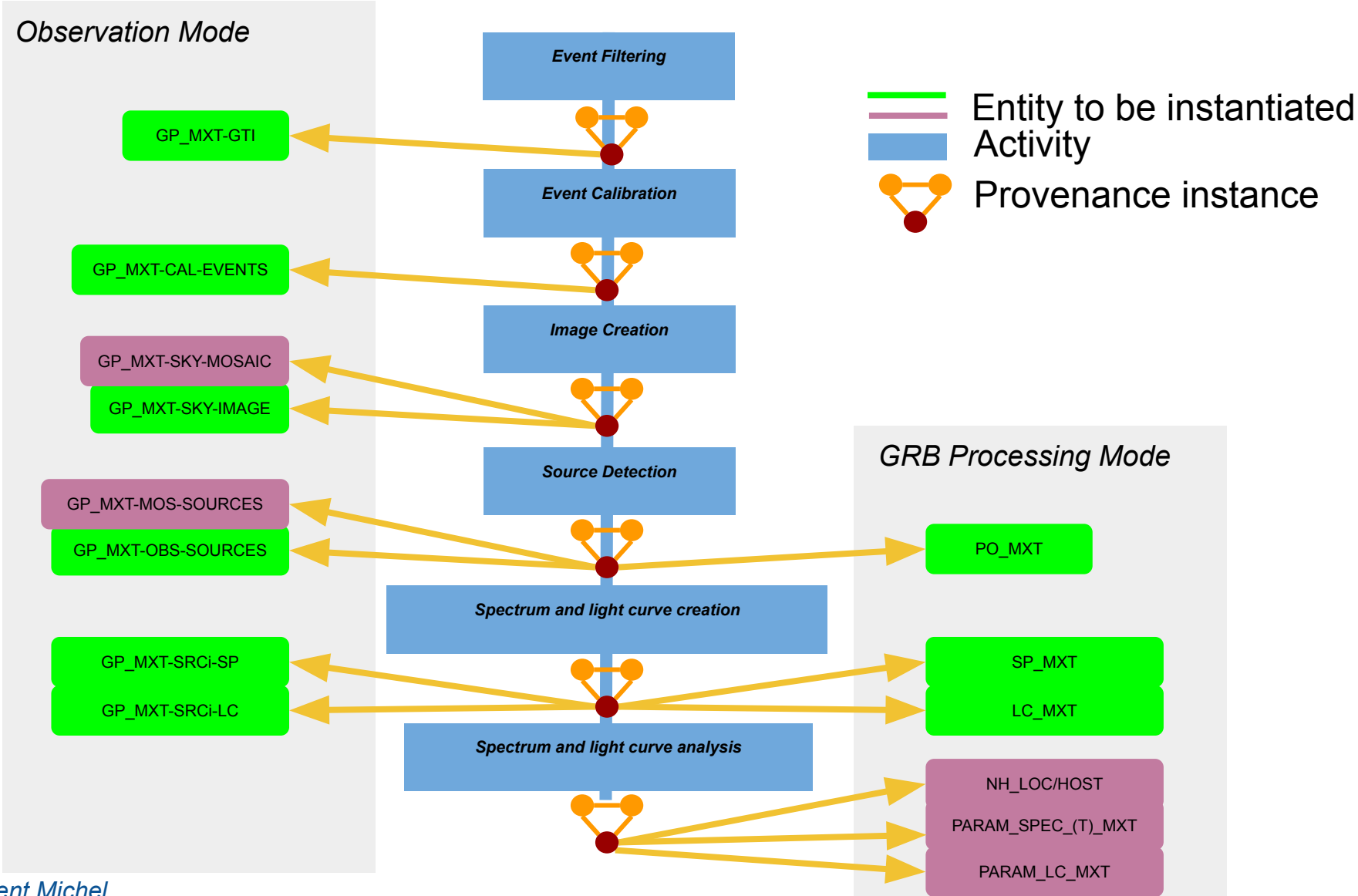


Provenance DM at a Glance

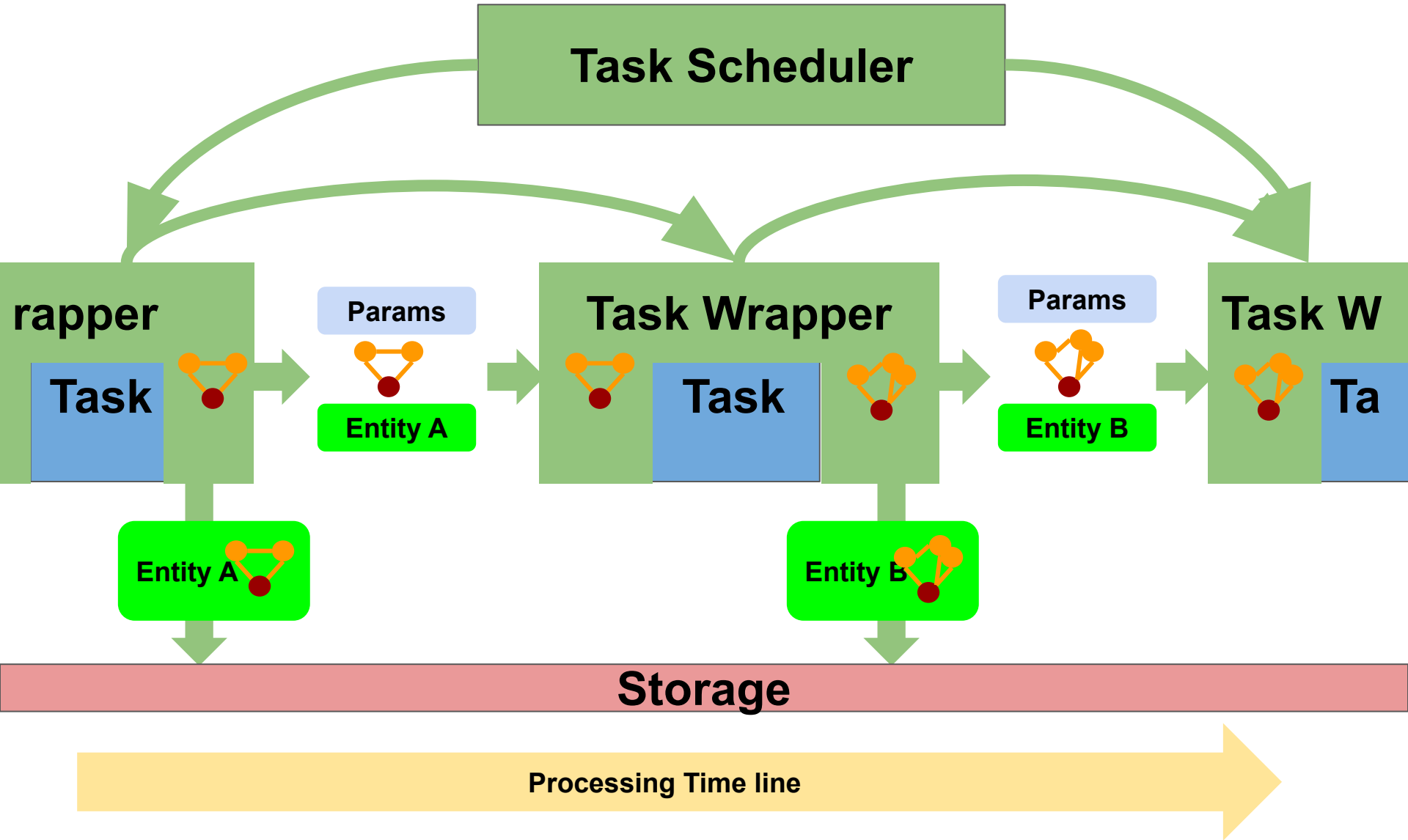
- Designed around 3 poles (*WARNING: the model has evolved since 2017*)
 - Activity, Agent and Entity
- **Prov Speaking: We want to describe the activities leading to our entities**
 - Entities are final science data files



Provenance View



Incremental Provenance Construction



Python Code Snippet

```
annotation = Annotation('../..../data/out.fits')
annotation.create_vo_extension()
annotation.set_obscore_keyword("DP_TYPE", "SPECTRUM");
```

```
prov_0 = {
  "top_entity": {
    "description": "",
    "name": "task0.out",
    "location": "./data",
    "was_generated_by": {
      "used_entities": [
        {
          "name": "DummyJob.py",
          "location": "./data",
          "was_generated_by": {}
        }
      ],
      "name": "task0",
      "configuration": {
        "parameters": [
          "task0",
          "0"
        ]
      }
    }
  }
}
```

```
annotation.store_provenance_string(json.dumps(prov_0, indent=2, sort_keys=True))
print(annotation.get_provenance_string())
annotation.commit()
```

```
"columns": ["vo_name", "fits_name", "description", "default_values", "allowed_values"],
"fields": [
  ["dataprodect_type", "DP_TYPE", "dataprodect_type", "", ["SPECTRUM", "IMAGE"]],
  ["calib_level", "CAL_LV", "calib_level (0 to 4)", "", [0, 1, 2, 3, 4]],
  ["target_name", "TARG_NM", "target_name", "", []],
  ["target_class", "TARG_CLA", "target_class", "", []],
  ["obs_id", "OBS_ID", "obs_id", "", []],
  ["obs_title", "OBS_TITL", "obs_title", "", []],
  ["obs_collection", "COLL_NM", "obs_collection", "", []],
  ["obs_creation_date", "CREA_DAT", "obs_creation_date (ISO 8601)", "", []],
  ["obs_release_date", "RLEA_DAT", "obs_release_date (ISO 8601)", "", []],
  ["obs_publisher_did", "PUB_DID", "obs_publisher_did", "", []],
  ["publisher_id", "PUB_ID", "obs_publisher_id", "", []],
  ["bib_reference", "BIB_REF", "bib_reference", "", []],
  ["data_rights", "PUB_ID", "data_rights", "", ["Public", "Secure", "Proprietary"]],
  ["access_url", "URL", "access_url", "", []],
  ["access_format", "FORMAT", "access_format", "application/fits", []],
  ["access_estsize", "EST_SIZE", "access_estsize", "", []],
  ["s_ra", "S_RA", "s_ra ICRS (deg)", "", []],
  ["s_dec", "S_DEC", "s_dec ICRS (deg)", "", []],
  ["s_fov", "S_FOV", "s_fov (de",
  ["s_region", "S_REGION", "s_r",
  ["s_resolution", "S_RES", "s_",
  ["s_ucd", "S_UCD", "s_ucd", "
  ["s_unit", "S_UNIT", "s_unit",
  ["s_calib_status", "S_CALST",
  ["s_stat_error", "S_STERR", "
  ["s_xel1", "S_XEL1", "s_xel1",
  ["s_xel2", "S_XEL2", "s_xel2",
  ["t_min", "T_MIN", "t_min (MJ",
  ["t_max", "T_MAX", "t_max (MJD)", "", []],
  ["t_resolution", "T_RES", "t_resolution (s)", "", []],
  ["t_calib_status", "T_CALST", "t_calib_status", "calibrated", ["uncalibrated", "raw", "cal",
  ["t_stat_error", "T_STERR", "t_stat_error", "", []],
  ["t_xel", "T_XEL", "t_xel", "", []]
```

OBSCORE model:

Mireille Louys (CDS) proposed a FITS-compliant version of the Obscore columns

VO Stuff with FV

fv: Summary of out.fits in /Us fv: Header of out.fits[1] in /Users/laurentmichel/git/pipeline-bi

Index	Extension	Type
<input type="checkbox"/> 0	Primary	Image
<input checked="" type="checkbox"/> 1	VO-TAGS	ASCII

```

XTENSION= 'TABLE'           / ASCII table extension
BITPIX   =                  8 / array data type
NAXIS    =                  2 / number of array dimensions
NAXIS1   =                  406 / length of dimension 1
NAXIS2   =                  1 / length of dimension 2
PCOUNT   =                  0 / number of group parameters
GCOUNT   =                  1 / number of groups
TFIELDS  =                  1 / number of table fields
TTYPE1   = 'provenance'
TFORM1   = 'A406'
TBCOL1   =                  1
EXTNAME  = 'VO-TAGS'       / extension name
DP_TYPE  = 'SPECTRUM'     / dataprodct_type
CAL_LV   = 'NotSet'       / calib_level (0 to 4)
TARG_NM  = 'NotSet'       / target_name
TARG_CLA = 'NotSet'       / target_class
OBS_ID   = 'NotSet'       / obs_id
OBS_TITL = 'NotSet'       / obs_tittle
    
```

File Edit Tools Hel

provenance
A406

Select
 All

Invert Modify

1 | {\n "top_entity": {\n "description": "",\n "location": ". /data",\n "name": "task0.out",\n "was_generated_by": {\n "configuration": {\n "paramete:

▶	entrypoint	S_DEC = 'NotSet' / s_dec ICRS (deg)
▶	httplib	S_FOV = 'NotSet' / s_fov (deg)
▶	messages	S_REGION= 'NotSet' / s_region ICRS
▶	pipeline	S_RES = 'NotSet' / s_resolution (arcsec)
▶	provenance	S_UCD = 'NotSet' / s_ucd
▶	ref_impl	S_UNIT = 'deg' / s_unit
▶	scheduler	S_CALST = 'calibrated' / s_calib_status
▶	_init_.py	S_STERR = 'NotSet' / s_stat_error
▶	.gitkeep	S_XEL1 = 'NotSet' / s_xel1
▶	configuration.py	S_XEL2 = 'NotSet' / s_xel2
▶	constants.py	T_MIN = 'NotSet' / t_min (MJD)
▶	execution_plan.py	T_MAX = 'NotSet' / t_max (MJD)
▶	io_management.py	T_RES = 'NotSet' / t_resolution (s)
▶	log_message.py	T_CALST = 'calibrated' / t_calib_status
▶	log_report.py	T_STERR = 'NotSet' / t_stat_error
▶	paramManagement.py	T_XEL = 'NotSet' / t_xel
		EM_MIN = 'NotSet' / em_min (m)
		EM_MAX = 'NotSet' / em_max (m)
		EM_UCD = 'NotSet' / em_ucd
		EM_UNIT = 'm' / em_unit
		EM_CALST= 'calibrated' / em_calib status